## Origins of jumping oscillons, reference sheet for JO1D,

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In [KUY21] we discuss the bifurcation of jumping oscillons (JOs) as modulated traveling waves (MTWs) from traveling waves (TWs) in the 3–component FHN type model,

$$\partial_t u = k_1 + k_2 u - u^3 - k_3 v - k_4 w + D_u \nabla^2 u + s \partial_x u,$$
  

$$\tau \partial_t v = u - v + D_v \nabla^2 v + \tau s \partial_x v,$$
  

$$\vartheta \partial_t w = u - w + D_w \nabla^2 w + \vartheta s \partial_x w,$$
  
(1)

following [YZE06], where  $k_{1,2,3,4} \in \mathbb{R}$  are parameters,  $D_{u,v,w} > 0$  are diffusion constants,  $\tau, \vartheta > 0$  are timescales, u = u(t, x) is an activator variable while v = v(t, x) and w = w(t, x)are inhibitors. The term  $s\partial_x U$ , U = (u, v, w) in (II) comes from going into a frame moving with speed s, such that we can compute TWs and MTWs as relative equilibria. The system has a unique uniform steady state  $U_* \equiv (u_*, v_*, w_*)^{\mathrm{T}}$ , and we mostly study bifurcations from  $U_*$  in  $\Omega = (-40, 40)$  with periodic boundary conditions (BCs), though for some computations of standing waves (SWs) and localized SWs (LSWs) (not discussed in [KUY21]) we consider (II) in  $\Omega = (-40, 40)$  with Neumann BCs. We refer to [KUY21] and the references therein for further discussion of the model, and to [Uec21] and the tutorials at [pde25] for general background and usage of pde2path, and here only comment on the implementation of (II) in pde2path underlying the results in [KUY21]. Table I lists the pertinent files.

**Remarks.** The J01D folder contains some somewhat advanced and experimental pde2path usage; most importantly, we use a quadratic finite element method (P2FEM, see assem1d2), which is in particular helpful to obtain a smooth behavior of the comoving frame speed s during continuation of TWs as relative equilibria with a non-small stepsize. Moreover, starting points for continuation of traveling pulses (TPs), aka localized traveling waves (LTWs), are obtained from first "chopping-off" TWs (i.e., replacing the spatially periodic TWs by  $U_*$  in parts of the domain) and then running numerical time integration, aka direct numerical simulation (DNS), to converge to TPs. A similar "chopping-off" is also used for SWs to obtain initial guesses for Newton–loops converging to localized standing waves (LSWs), which then yield snaking branches of LSWs (not shown in [KUY21]). However, in particular the convergence to LSWs after chopping-off SWs depends rather sensitively on the exact way of choppingoff. Finally, we also use chopping off and DNS to obtain convergence to TP–JO mixed mode bound states [KUY21, Fig.1], which again depends sensitively on the chop-off details. Thus, though the continuation and bifurcation methods in JO1D are standard, the folder contains some somewhat experimental (or "trial-and-error" and "trial-and-success") procedures to obtain initial points for continuation.

Table 1: Scripts and functions in JO1D. Associated to some cmds\*-scripts are cmds\*plot scripts for plotting; all figure numbers refer to [KUY21]. 1st block: scripts; 2nd block: problem describing functions and overloads of pde2path library functions; 3rd block: convenience functions.

file	purpose, remarks
cmdsTW	Main script for TWs, localized TWs (LTWs) and mTWs, i.e., JOs, over $\Omega =$
	$(-40, 40)$ with periodic BCs. First we continue the trivial branch $U_*$ in $k_1$ (output
	to b/Opbc) and then use twswibra to switch to (spatially periodic) TWs, with
	the speed $s$ as a secondary parameter, using the standard phase condition (PC)
	$q(u) = \int (\partial_x U_{\text{old}}) U  \mathrm{d}x  [\text{KUY21}, (3)], \text{ where } U_{\text{old}} \text{ is the solution from the last step.}$

	We then obtain "localized" TWs (LTWs, aka traveling pulses, TPs) by "chopping
	off" TWs, i.e., replacing by $U_*$ all but one of the waves in a periodic TW and
	runing DNS. After convergence, we can then continue the LTWs again as relative
	equilibria, with some snaking behavior as additional pulses are added to the initial
	1-pulse, and on the resulting branch there are Hopf points (HPs) to MTWs.
	After hoswibra from the HPs on the LTW branch, we switch to the average PC
	[KUY21, (4)]; the resulting MTW branch turns into a branch of stable 1–peak
	JOs after a first fold, and subsequently shows some further snaking behavior
	where the 1-peak JOs turn into $m$ -peak JOs ( $m \ge 2$ ).
cmdsTWplot	plotting of results from cmdsTW, Figs.1-2.
cmdsSW	compute the trivial branch with Neumann BCs (output to b/0, and then use
	hoswibra to switch to SWs (no PC needed due to the Neumann BCs). Then
	use some cut–off SW as an initial guess for a Newton loop which converges to a
	LSW. Continuing this in $k_1$ yields a snaking LSW branch which adds/takes away
	another wave in every second folds. Plotting of this directly at the end of cmdsSW
	(not shown in [KUY21]).
cmdsdisp	plot dispersion relations for linearization of (II) around $U_*$ [KUY21, Fig.S1]. In-
	dependent of domain, hence using a small domain.
cmdsdns1	DNS from various initial guesses, yielding various $nTP-mJO$ bound states as in
	Fig.1.
dns2hopf	sample script how to use DNS to generate time periodic states (JOs) for contin-
	uation.
yzeinit	initialization of problem struct p with standard parameter values, call of
yzeinit	initialization of problem struct <b>p</b> with standard parameter values, call of <b>stanpdeo1D</b> to generate a 1D PDE object (interval, with mesh), initialization
yzeinit	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original
yzeinit	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass ma-
yzeinit	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path
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yzeinit oosetfemops	initialization of problem struct $\mathbf{p}$ with standard parameter values, call of <b>stanpdeo1D</b> to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of <b>assem1d2</b> to generate a P2–FEM mesh from the original (P1) mesh and from the P2–mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) Neumann Neum
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yzeinit oosetfemops	initialization of problem struct $\mathbf{p}$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in $\mathbf{p}$ .mat. oosetfemops is called after loading a point since $\mathbf{p}$ .mat is not saved to disk.
yzeinit oosetfemops sG,sGjac	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (II), and Jacobian; these here have a simple standard structure.
yzeinit oosetfemops sG,sGjac nodalf	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (Il), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs.
yzeinit oosetfemops sG,sGjac nodalf nodaljac	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (II), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs. Jacobian of "nonlinearity", called in sGjac.
yzeinit oosetfemops sG,sGjac nodalf nodaljac hobra,	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (II), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs. Jacobian of "nonlinearity", called in sGjac. mods of respective library functions.
yzeinit oosetfemops sG,sGjac nodalf nodaljac hobra, hobratw	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (II), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs. Jacobian of "nonlinearity", called in sGjac.
yzeinit oosetfemops sG,sGjac nodalf nodaljac hobra, hobratw assem1d2	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (I), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs. Jacobian of "nonlinearity", called in sGjac. mods of respective library functions.
yzeinit oosetfemops sG,sGjac nodalf nodaljac hobra, hobratw assem1d2 bdmovJO	initialization of problem struct $p$ with standard parameter values, call of stanpdeo1D to generate a 1D PDE object (interval, with mesh), initialization of $u$ with $u^*$ , call of assem1d2 to generate a P2-FEM mesh from the original (P1) mesh and from the P2-mesh generate the stiffness matrix $K$ , the mass matrix $M$ and the convection matrix $K_x$ , and finally resetting of some pde2path parameters to problem adapted values. assemble the mass matrix $M$ , and the (1-component) Neumann-Laplacian $K$ and the (1-component) convection matrix $K_x$ . For the case of periodic BCs, these are then also converted via filltrafo, and then stored in p.mat. oosetfemops is called after loading a point since p.mat is not saved to disk. rhs of (II), and Jacobian; these here have a simple standard structure. "nonlinearity", i.e., terms without spatial derivatives, called in hotintxs. Jacobian of "nonlinearity", called in sGjac. mods of respective library functions.

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